



Micro:Maqueen Robot Car(V2.0)

SKU: ROB0148

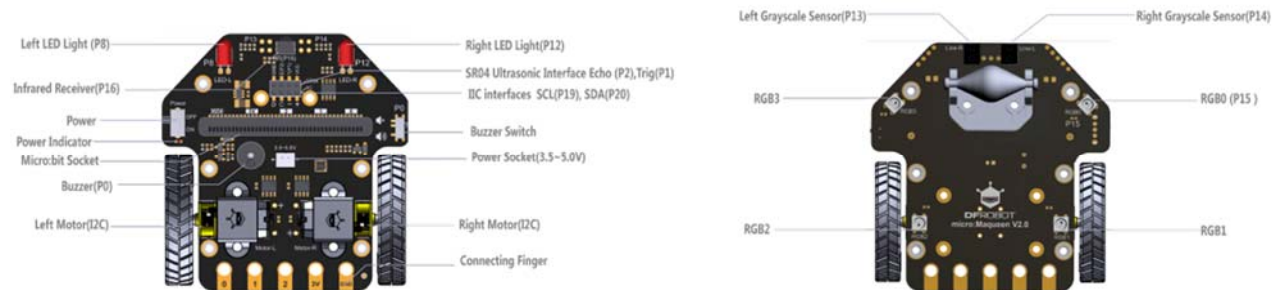
I am Maqueen

Hello, my name is Maqueen, is a graphical programming robot for STEM education, which inherits playability and simple operation of micro:bit. The Mini-body, interesting features and plug-and-play allow children to quickly learn graphic programming in entertaining, nurturing children's interest in science and logical thinking.

What are the features of Maqueen?

- Support for Makecode, will support Scratch and python later.
- Small size, flexible movement.
- All-metal miniature gear motor, good quality, strong driving force.
- Line patrol, ambient light, LED lights, ultrasonic interface, buzzer, I2C interface, mechanical expansion screw hole, etc. ... full-featured, highly expandable.
- Exclusive customized POM bearing wheel, flexible and reliable, strong obstacle crossing ability.
- Easy to install, easy to use.

Function Diagram



Specification

- Supply Voltage: 3.5V~5V DC (Three AAA batteries or 3.7V lithium battery)
- Infrared Grayscale Sensor(High-low level) x 2
- Buzzer x 1
- Infrared Receiver (NEC decoder) x 1
- LED Lights (High-low level control) x 2
- RGB Ambient Light (16 million colors) x 4
- SR04, SR04P Ultrasonic Interface
- IIC Interface (3.3V) x 1
- N20 All-metal Gear Motor x 2
- Motor Reduction Ratio: 1:150
- Maximum Rotate Speed: 133 rpm
- Motor Drive Mode: PWM motor drive
- Bracket and Protective Cover Extension M3 Screw Hole x 6
- Programming Method: Makecode graphical programming, Mind + graphical programming (based on Scratch 3.0)
- Dimension: 81mm x 85 mm x 44mm/3.19 x 3.35 x 1.73in
- Weight: 75.55g

Product Configuration List

- Car Body x 1
- Wheel x 2
- Three AAA batteries Box x 1
- Double Sided Adhesive Tape x 1

Product Installation



Import the Makecode Graphical Library

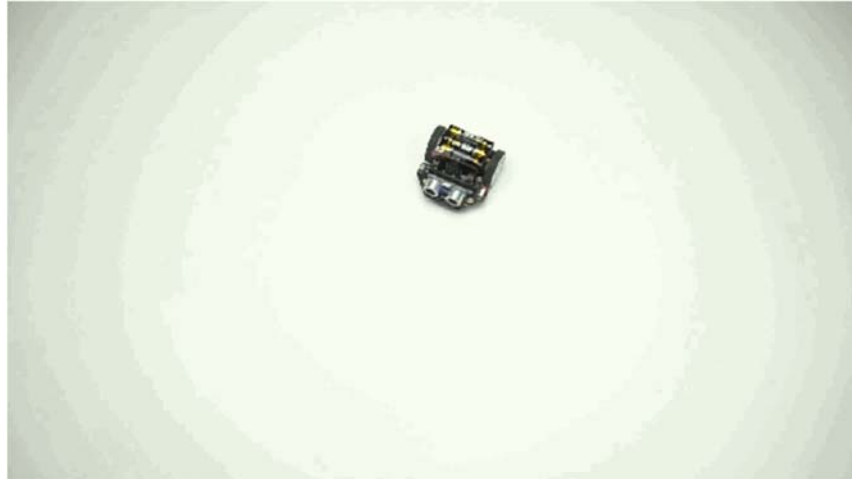
1. Click the link: makecode.microbit.org, enter the makecode graphical online programming platform. (Note: Loading will be slow in the first time, please wait patiently)
2. Import the library: Copy the Maqueen library's address: <https://github.com/jhlucky/maqueen>
3. Import the library by following the steps.

Makecode Programming Example

Motor Control

Learning Target: Mastering the basic method of motor control.

Effect: The car forward 1 second, right turn 1 second, left turn 1 second, back 1 second, back and right turn 1 second.



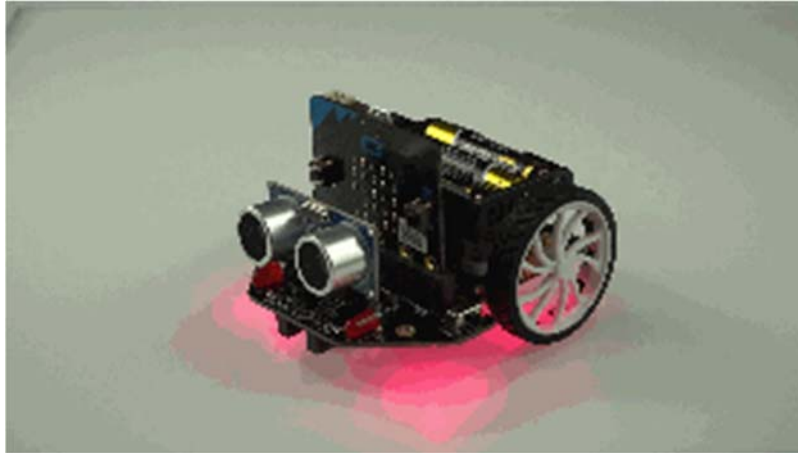
Makecode Program Link: https://makecode.microbit.org/_2Cc9gM5P5aDs
Screenshot of Makecode Graphical Program:

```
forever
  Motor M1 dir CW speed 255
  Motor M2 dir CW speed 255
  pause (ms) 1000
  Motor M1 dir CW speed 255
  Motor M2 dir CW speed 0
  pause (ms) 1000
  Motor M1 dir CW speed 0
  Motor M2 dir CW speed 255
  pause (ms) 1000
  Motor M1 dir CCW speed 255
  Motor M2 dir CCW speed 255
  pause (ms) 1000
  Motor M1 dir CCW speed 255
  Motor M2 dir CCW speed 0
  pause (ms) 1000
```

RGB Breathing Ambient Light

Learning Target: Learn the basic way of using ambient light.

Effect: The RGB ambient light at the bottom of the Maqueen shows a variety of colors and presents a gradient effect.



Makecode Program Link: https://makecode.microbit.org/_WkgPLpAotP3f

Screenshot of Makecode Graphical Program:

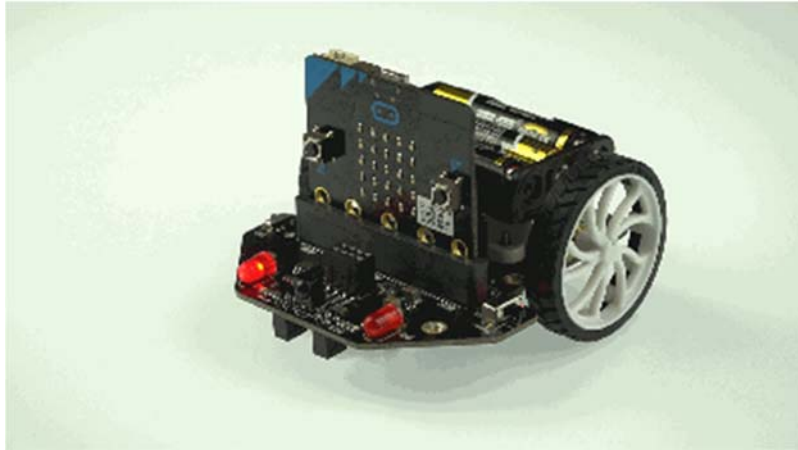
```
on start
  set item to NeoPixel at pin P15 with 4 leds as RGB (GRB format)

forever
  set RED to 0
  set GREEN to 0
  set BLUE to 255
  repeat 255 times
    do
      change RED by 1
      change BLUE by -1
      item show color red RED green GREEN blue BLUE
      pause (ms) 1
  repeat 255 times
    do
      change GREEN by 1
      change RED by -1
      item show color red RED green GREEN blue BLUE
      pause (ms) 1
  repeat 255 times
    do
      change BLUE by 1
      change GREEN by -1
      item show color red RED green GREEN blue BLUE
      pause (ms) 1
```

LED Light Flash

Learning Target: Learn the using way of LED light and buzzer.

Effect: The left and right LED lights flash alternately, and the buzzer emits two different tone frequencies at intervals of 500 milliseconds.



Makecode Program Link:https://makecode.microbit.org/_6gKRm1RVsDxY

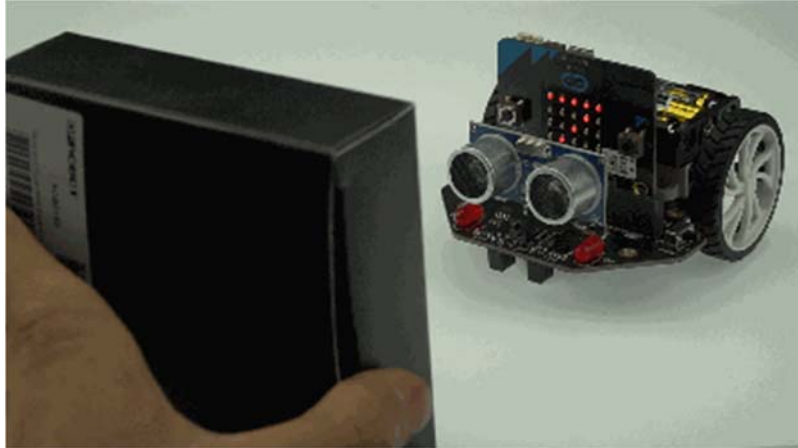
Screenshot of Makecode Graphical Program:



Read Ultrasonic Distance

Learning Target: Learn to read the distance of ultrasound, so that later can be flexible use of these data.

Effect: The ultrasonic detects the obstruction in front and the distance will be displayed on the dot-matrix screen in centimeters.



Makecode Program Link: https://makecode.microbit.org/_4qi4Di7yTWgK
Screenshot of Makecode Graphical Program:



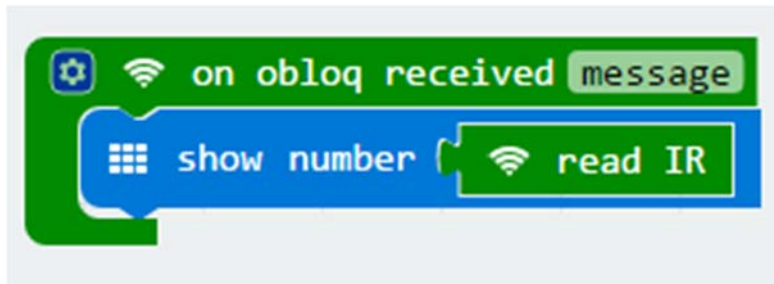
Read Infrared Key Assignments

Learning Target: Learn to read the key assignments of infrared, so that later can be flexible use of these data.

Effect: Put the the IR receiver toward the IR remote control, when you press any key on the IR remote control. The key assignments that corresponds to the pressed key will displayed on the dot matrix, in decimal notation the last two digits of the key assignments are displayed.



Makecode Program Link: https://makecode.microbit.org/_361V7bbp0UAq
Screenshot of Makecode Graphical Program:



IR Remote Control and Its Key Assignments

The key assignments in the following table are in hexadecimal. In this product, we read the last two digits of the key assignments and automatically convert them to decimal data.

Key	Key Assignments
Power	0xff00
VOL+	0xfe01
FUNC/STOP	0xfd02
Left	0xfd04
Pause	0xfa05
Right	0xf906
Down	0xf708
VOL-	0xf609
Up	0xf50a
0	0xf30c
EQ	0xf20d
ST/REPT	0xf10e
1	0xef10
2	0xee11
3	0xfa05

4	0xeb14
5	0xea15
6	0xe916
7	0xe718
8	0xe619
9	0xe51a

IR Remote Control

Learning Target : Learn to use the IR remote control to command the car.

Effect: Control car forward, left, right, back with 4 keys of IR remote control 2, 4, 6, 8.



Makecode Program Link: https://makecode.microbit.org/_MfDXhX6MM35X

Screenshot of Makecode Graphical Program:

The image shows a Scratch script for controlling a robot. The script starts with an "on obloq received message" event. It contains five conditional blocks, each triggered by a specific message value. Each block contains actions for two motors (M1 and M2) and two LEDs (LEDLeft and LEDRight).

```
on obloq received message
  if (message = 17) then
    Motor M1 dir CW speed 150
    Motor M2 dir CW speed 150
    led LEDLeft ledswitch turnOn
    led LEDRight ledswitch turnOn

  if (message = 25) then
    Motor M1 dir CCW speed 150
    Motor M2 dir CCW speed 150
    led LEDLeft ledswitch turnOff
    led LEDRight ledswitch turnOff

  if (message = 20) then
    Motor M1 dir CW speed 0
    Motor M2 dir CW speed 150
    led LEDLeft ledswitch turnOn
    led LEDRight ledswitch turnOff

  if (message = 22) then
    Motor M1 dir CW speed 150
    Motor M2 dir CW speed 0
    led LEDLeft ledswitch turnOff
    led LEDRight ledswitch turnOn

  if (message = 21) then
    Motor Stop All
    led LEDLeft ledswitch turnOff
    led LEDRight ledswitch turnOff
```

Detailed description of the code blocks:

- Block 1:** Triggered by message 17. Both Motor M1 and Motor M2 rotate clockwise (CW) at speed 150. Both LEDLeft and LEDRight are turned on.
- Block 2:** Triggered by message 25. Both Motor M1 and Motor M2 rotate counter-clockwise (CCW) at speed 150. Both LEDLeft and LEDRight are turned off.
- Block 3:** Triggered by message 20. Motor M1 is stopped (speed 0), while Motor M2 rotates clockwise (CW) at speed 150. LEDLeft is turned on, and LEDRight is turned off.
- Block 4:** Triggered by message 22. Motor M1 rotates clockwise (CW) at speed 150, while Motor M2 is stopped (speed 0). LEDLeft is turned off, and LEDRight is turned on.
- Block 5:** Triggered by message 21. All motors are stopped. Both LEDLeft and LEDRight are turned off.

Line-tracking

Effect: The car is running along the black line.



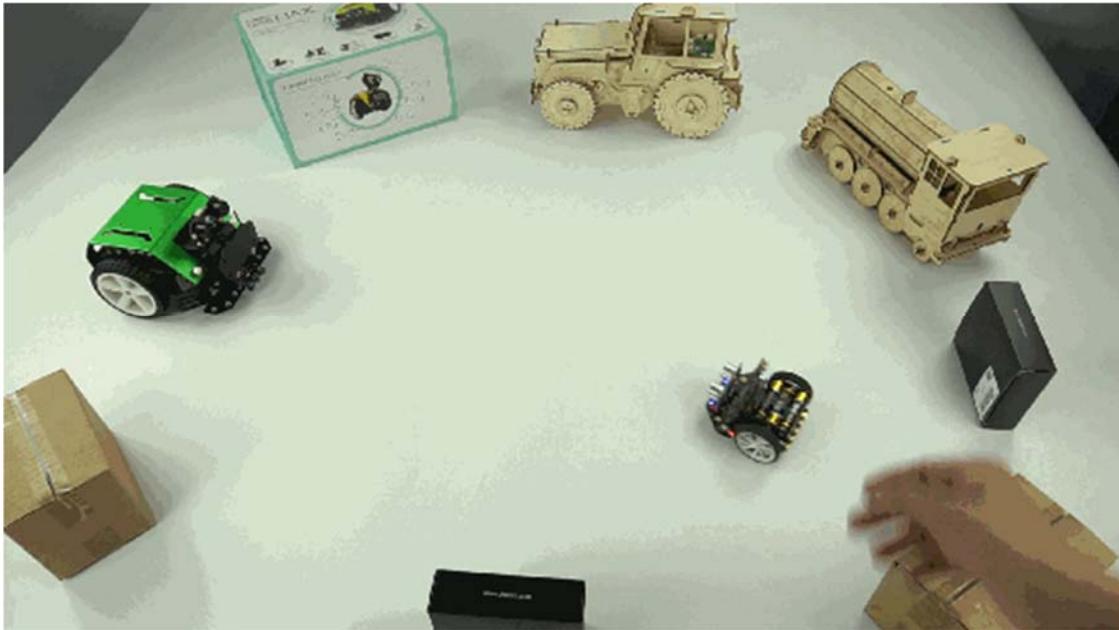
Makecode Program Link: <https://makecode.microbit.org/1VzX7LLAC3im>
Screenshot of Makecode Graphical Program:

```
forever loop
  if (Read Patrol PatrolLeft == 0 and Read Patrol PatrolRight == 0)
  then
    Motor M1 dir CW speed 255
    Motor M2 dir CCW speed 255
  else
    if (Read Patrol PatrolLeft == 0 and Read Patrol PatrolRight == 1)
    then
      Motor M1 dir CW speed 0
      Motor M2 dir CCW speed 255
      if (Read Patrol PatrolLeft == 1 and Read Patrol PatrolRight == 1)
      then
        Motor M1 dir CW speed 0
        Motor M2 dir CCW speed 255
    else
      if (Read Patrol PatrolLeft == 1 and Read Patrol PatrolRight == 0)
      then
        Motor M1 dir CW speed 255
        Motor M2 dir CCW speed 0
      if (Read Patrol PatrolLeft == 1 and Read Patrol PatrolRight == 1)
      then
        Motor M1 dir CW speed 255
        Motor M2 dir CCW speed 0
      if (Read Patrol PatrolLeft == 1 and Read Patrol PatrolRight == 0)
      then
        Motor M1 dir CW speed 255
      else
        Motor M2 dir CCW speed 0
```

Ultrasonic Obstacle-avoiding

Effect: Ultrasonic detects the distance between the car and the obstacle in front of it. If the distance is less than 35cm, the car will randomly choose to turn left or right to avoid obstacles.

Fittings: SR04 Ultrasonic Module x 1 or SR04-P Ultrasonic Module x 1



Makecode Program Link: https://makecode.microbit.org/_Fa4Ef3DwyXW7

Screenshot of Makecode Graphical Program:

```
forever
  if (sensor unit cm < 35 and sensor unit cm > 0)
  then
    set item to pick random true or false
    if (item == true)
    then
      Motor M1 dir CW speed 255
      Motor M2 dir CW speed 0
      pause (ms) 800
    if (item == false)
    then
      Motor M1 dir CW speed 0
      Motor M2 dir CW speed 255
      pause (ms) 800
  else
    Motor M1 dir CW speed 255
    Motor M2 dir CW speed 255
```

Light-operated Sprite

Effect: The car does not move in the darker light, and as the flashlight illuminates the LED, the vehicle's forward speed begins to increase as the intensity of the light increases.



Makecode Program Link: <https://makecode.microbit.org/fi6DWjCKeM9v>
Screenshot of Makecode Graphical Program:

```
forever
  if (light level > 70)
  then
    Motor M1 dir CW speed light level
    Motor M2 dir CW speed light level
  else
    Motor Stop All
```

Wireless Remote Control

Learning Target: Learn the way of using micro:bit wireless.

Effect: Use gamepad to control the car's movement.

micro:bit Micro:bit Gamepad

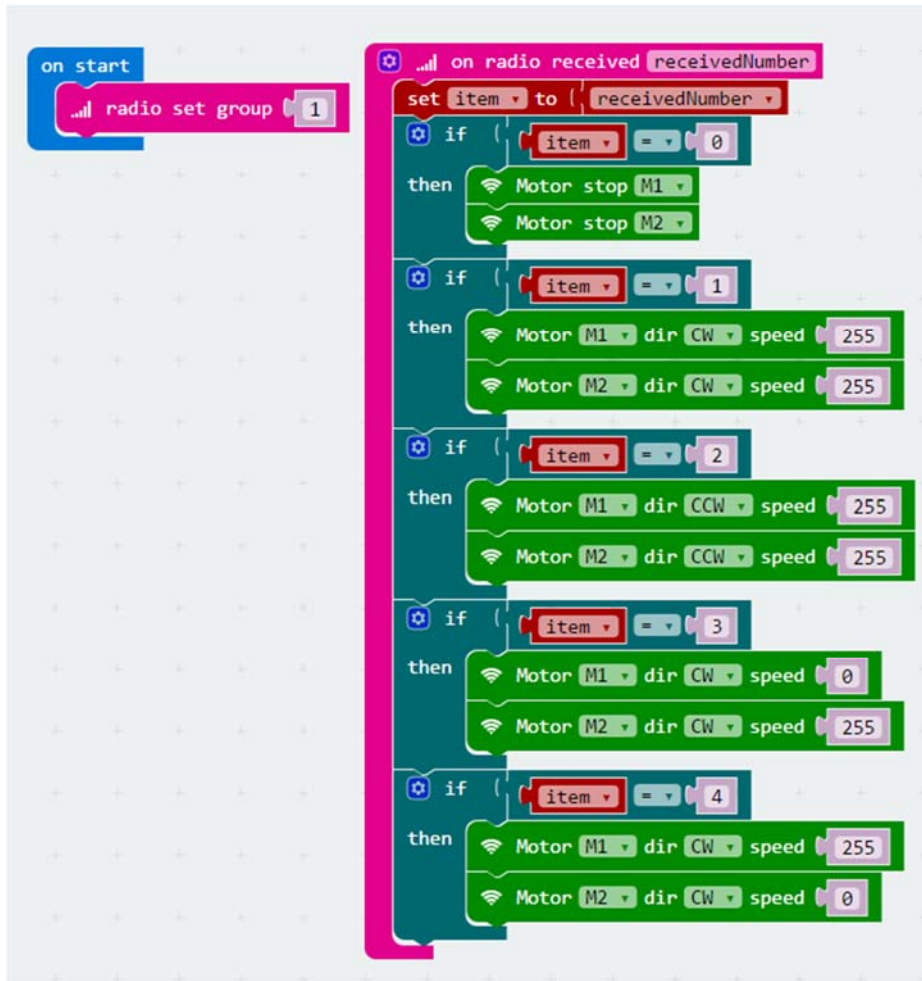


Makecode Program Link of the Car:<https://makecode.microbit.org/ftMMb8WkwDV7>

Makecode Program Link of the Gamepad: <https://makecode.microbit.org/qwK0A3JwEW0V>

Screenshot of Makecode Graphical Program:

- Screenshot of Car's Makecode Graphical Program:



- Screenshot of Gamepad's Makecode Graphical Program:

